

# Walk through Deep Transfer Learning

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12.7.2018

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# Introduction

## Transfer Learning

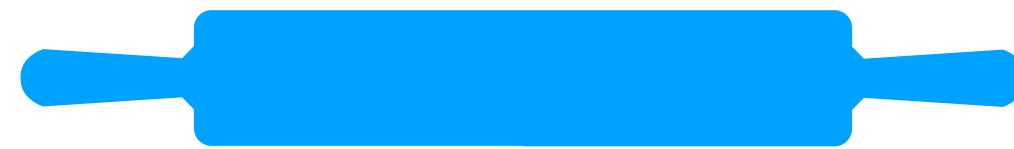


The application of skills, knowledge, and/or attitudes that were learned in one situation to another **learning** situation (Perkins, 1992)

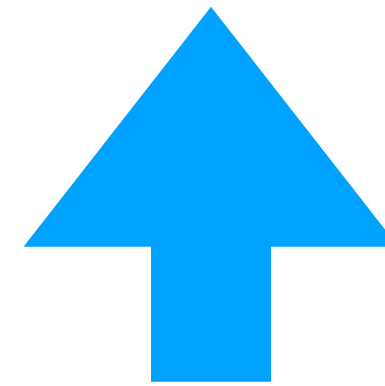


# Introduction

Transfer Learning



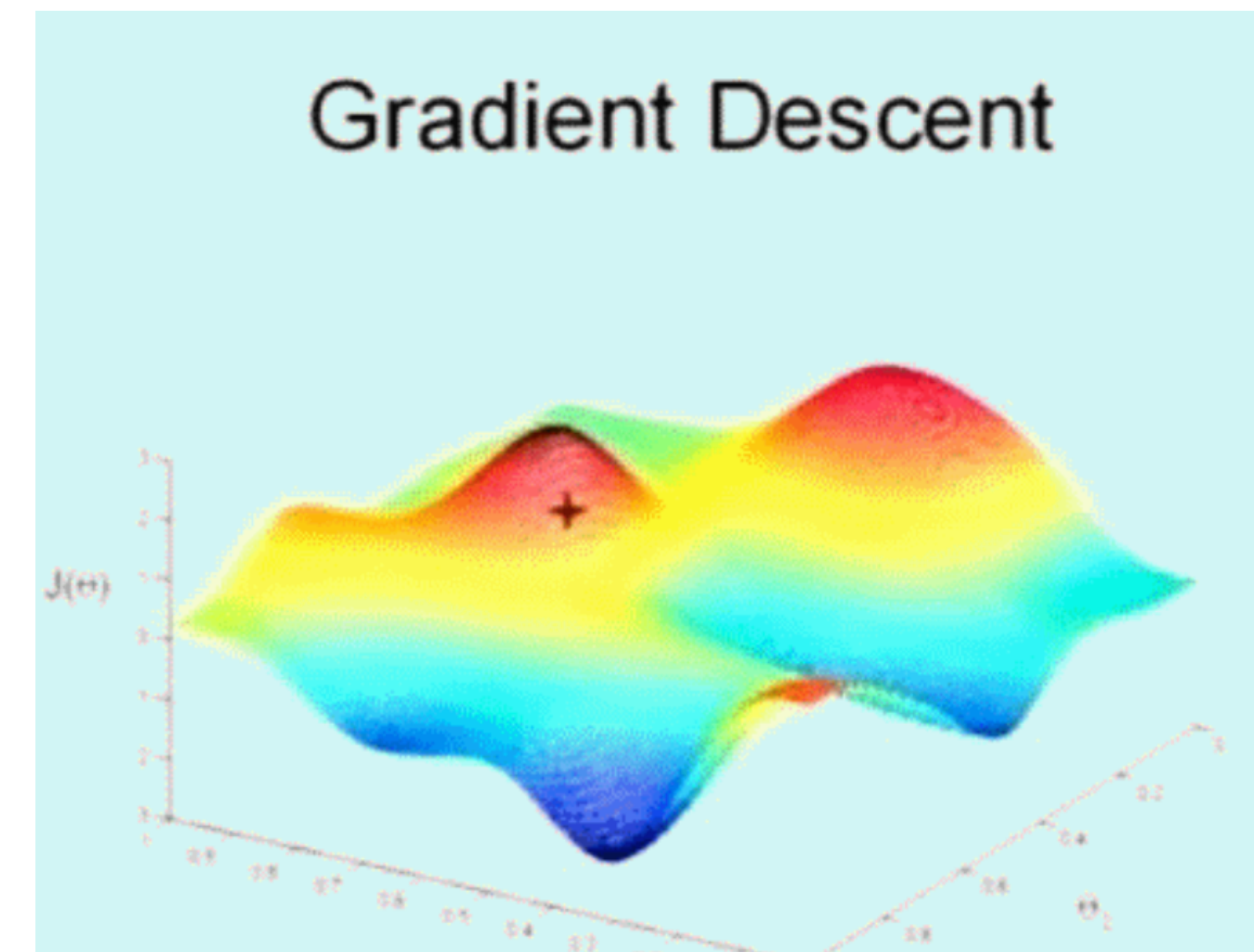
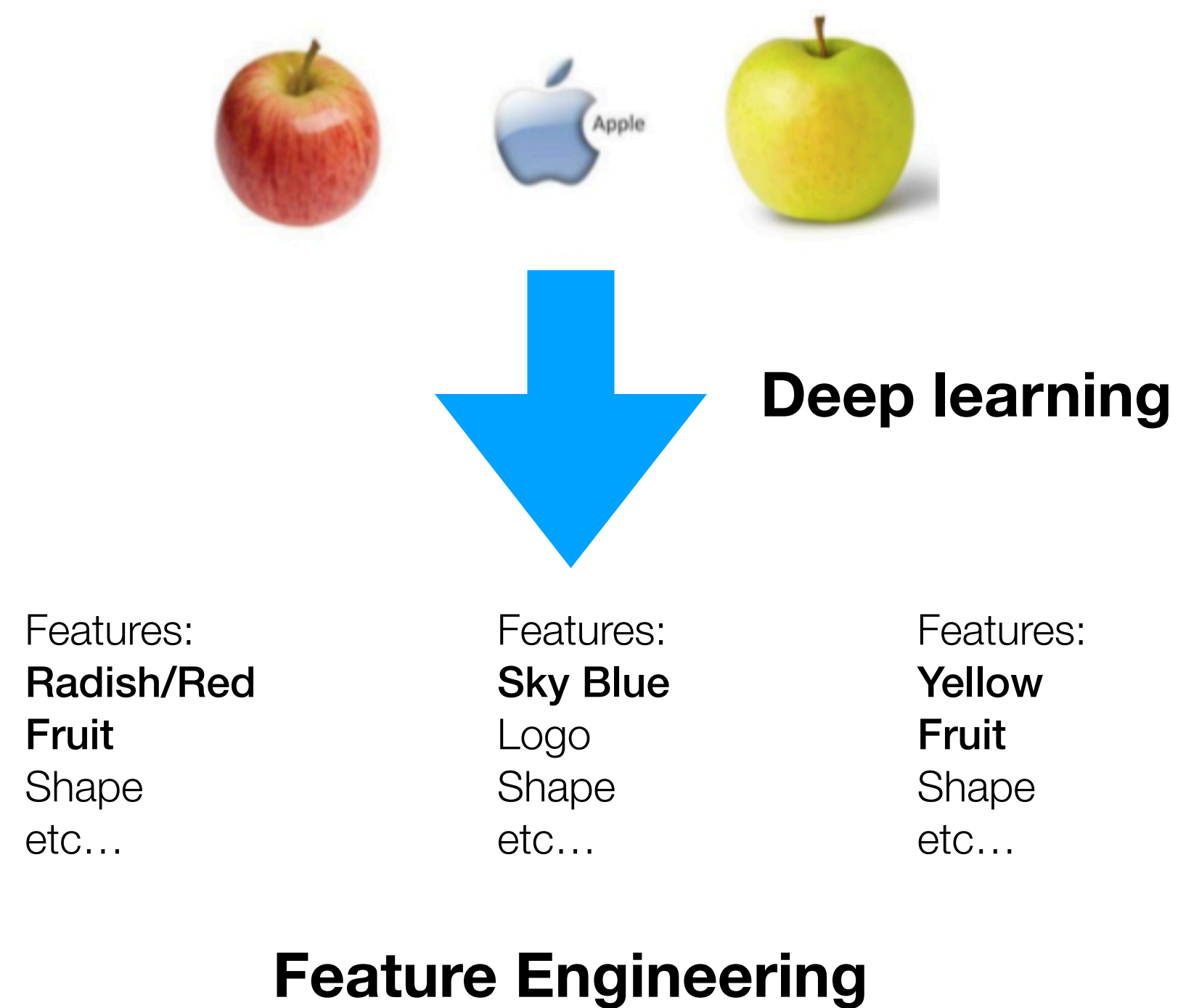
Deep Learning



- Big data
- Powerful computation
- New algorithmic techniques
- Mature software packages and architectures
- .....

# Introduction

## Why is deep learning so significant?

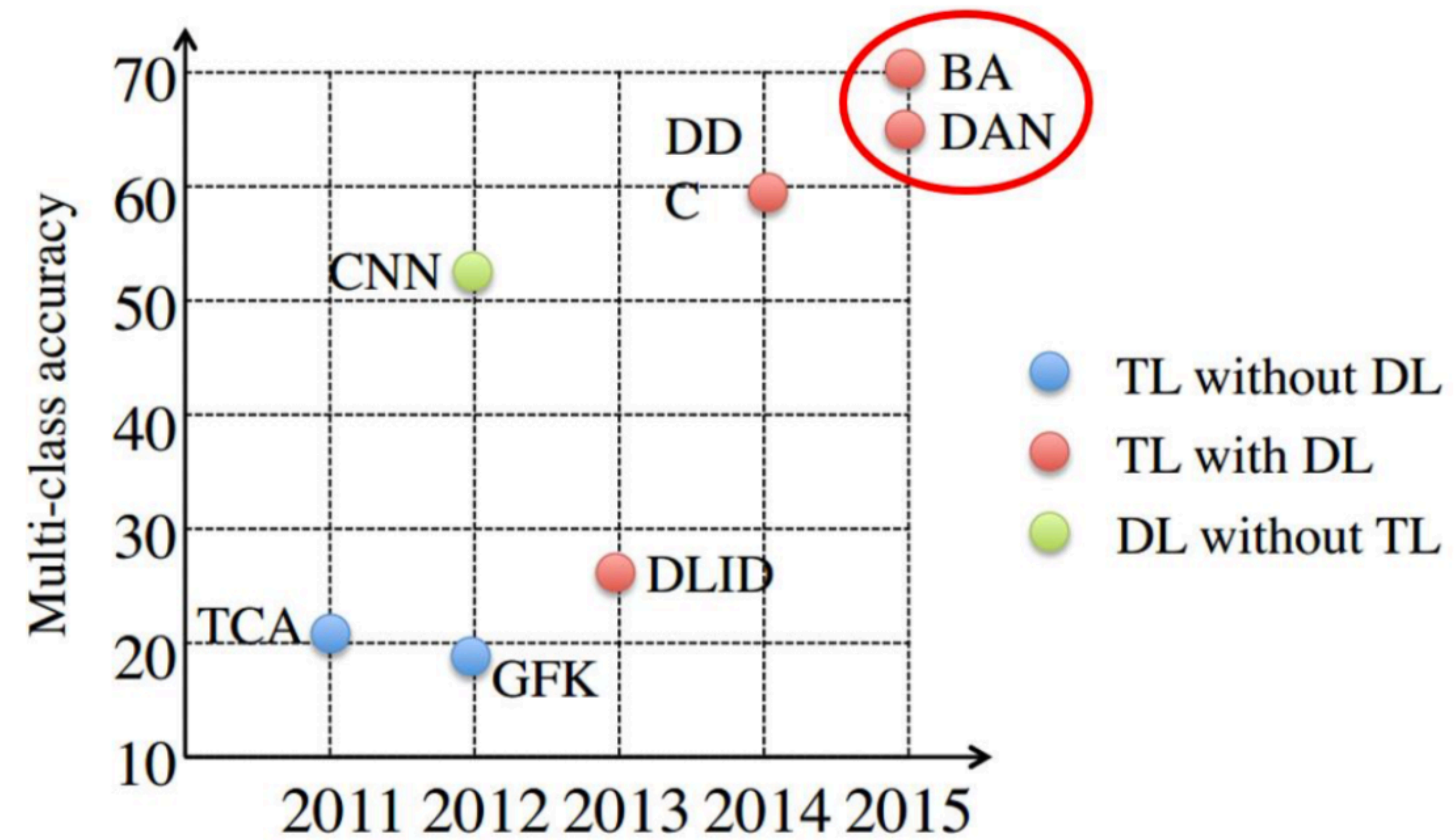


**End-to-end learning  
through gradient descent**



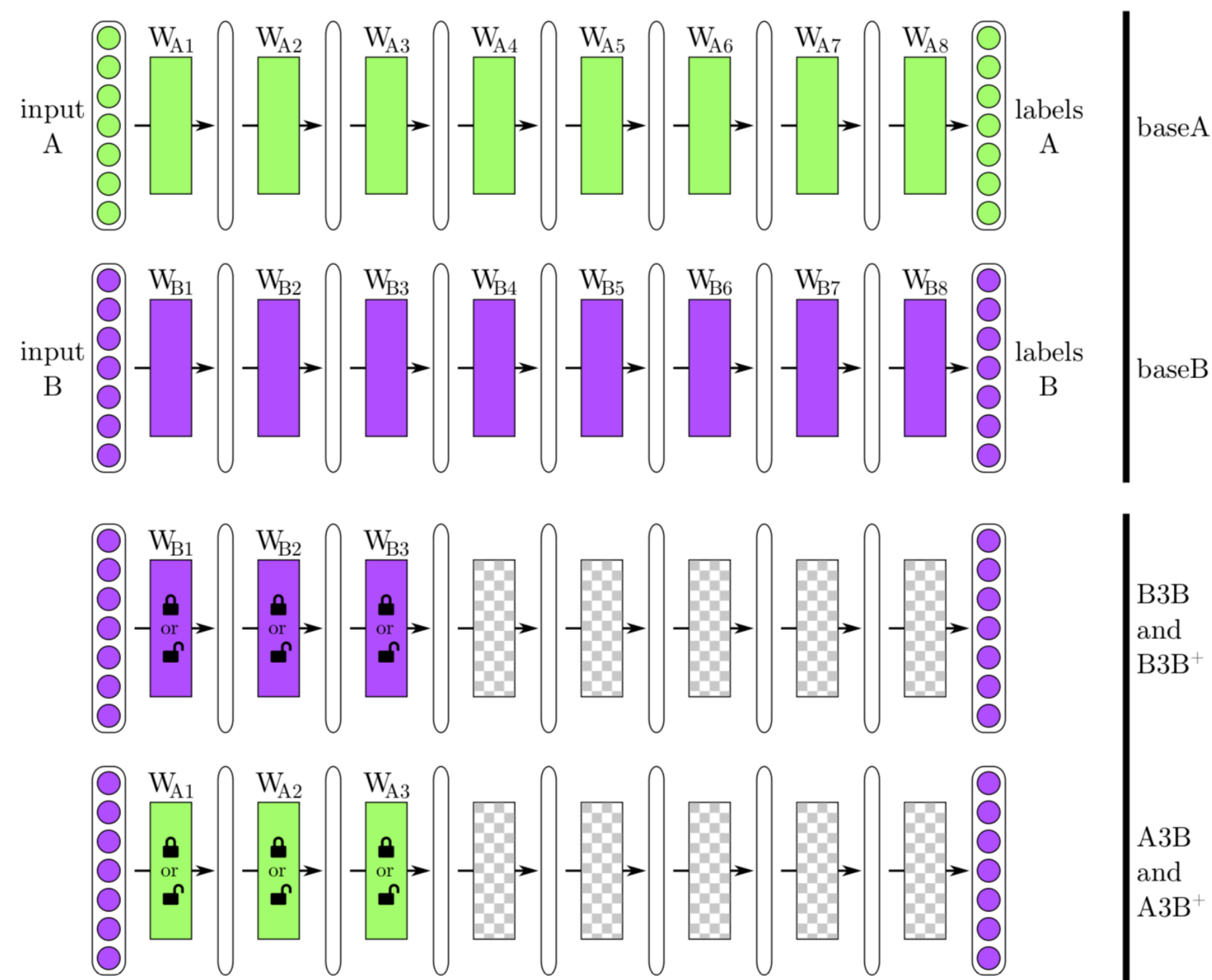
# Introduction

## Comparison



# Introduction

## How transferable are features in deep neural networks? [1]

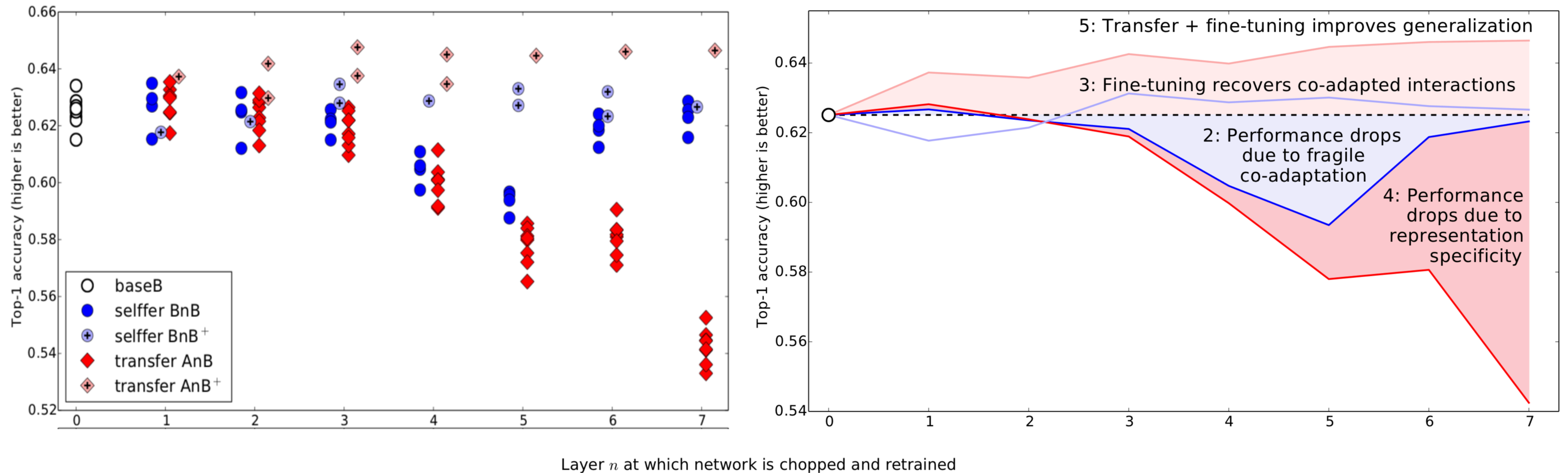


- BnB: First n layers are copied from base B and frozen. Others are randomly initialized.
- AnB: First n layers are copied from base A and frozen. Others are randomly initialized.
- BnB<sup>+</sup>: BnB but all layers trainable.
- AnB<sup>+</sup>: AnB but all layers trainable.

[1] Yosinski, J., Clune, J., Bengio, Y., and Lipson, H. How transferable are features in deep neural networks? In NeurIPS, 2014

# Introduction

## How transferable are features in deep neural networks?





# Introduction

**How transferable are features in deep neural networks?**

Conclusion of the paper:

- The first 3 layers are general.
- Fine-tune improves performance notably.
- By Fine-tuning data from different domain can be used.
- Deep transfer networks are better than randomly initialized ones.

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# Core Methods

Why we need domain transfer methods?

	Train set		Test set	
Source domain	$x_S$	$y_S$	\	\
Target domain	$x_T$	$y_T$	$x_T$	?

In fine-tune method,  $y_T$  is needed!

# Core Methods

## Domain Adaptive Neural Networks for Object Detection [2]

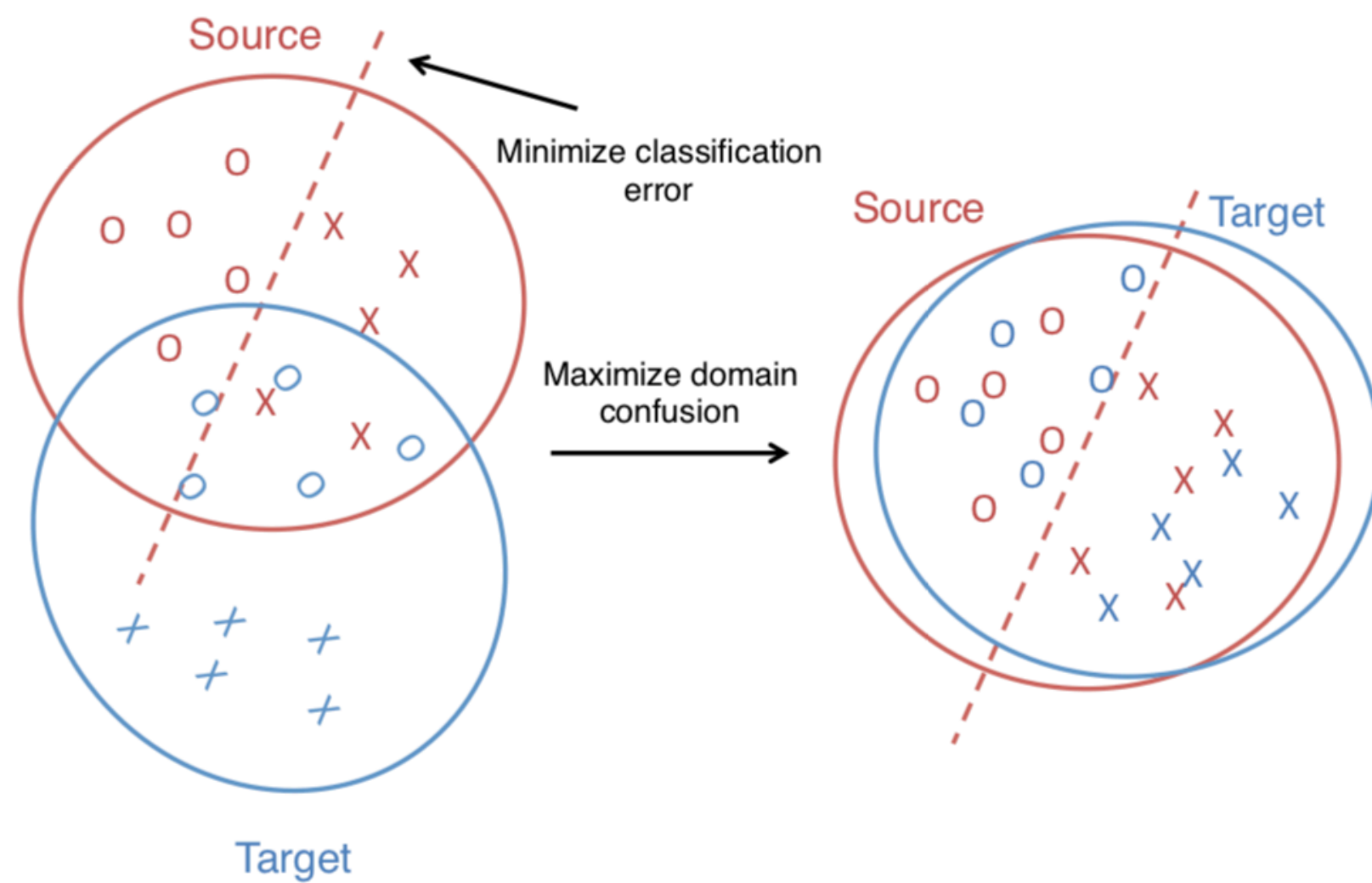
Maximum Mean Discrepancy (MMD):

$$\begin{aligned} \mathcal{MMD}_e(\mathbf{x}_s, \mathbf{x}_t) &= \left\| \frac{1}{n_s} \sum_{i=1}^{n_s} \phi(\mathbf{x}_s^{(i)}) - \frac{1}{n_t} \sum_{j=1}^{n_t} \phi(\mathbf{x}_t^{(j)}) \right\|_{\mathcal{H}} \\ &= \left( \frac{1}{n_s^2} \sum_{i=1}^{n_s} \sum_{j=1}^{n_s} k(\mathbf{x}_s^{(i)}, \mathbf{x}_s^{(j)}) + \frac{1}{n_t^2} \sum_{i=1}^{n_t} \sum_{j=1}^{n_t} k(\mathbf{x}_t^{(i)}, \mathbf{x}_t^{(j)}) \right. \\ &\quad \left. - \frac{2}{n_s n_t} \sum_{i=1}^{n_s} \sum_{j=1}^{n_t} k(\mathbf{x}_s^{(i)}, \mathbf{x}_t^{(j)}) \right)^{\frac{1}{2}} \\ &= \left( \frac{\text{Tr}(\mathbf{K}_{xss})}{n_s^2} + \frac{\text{Tr}(\mathbf{K}_{xtt})}{n_t^2} - 2 \frac{\text{Tr}(\mathbf{K}_{xst})}{n_s n_t} \right)^{\frac{1}{2}}, \end{aligned}$$

[2] Muhammad Ghifary, W. Bastiaan Kleijn, and Mengjie Zhang. Domain Adaptive Neural Networks for Object Recognition. In PRICAI, 2014

# Core Methods

## Domain Adaptive Neural Networks for Object Detection



Joint loss function:

$$J_{\text{DaNN}} = J_{\text{NN}_s} + \gamma \mathcal{MMD}_e^2(\mathbf{q}_s, \bar{\mathbf{q}}_t),$$

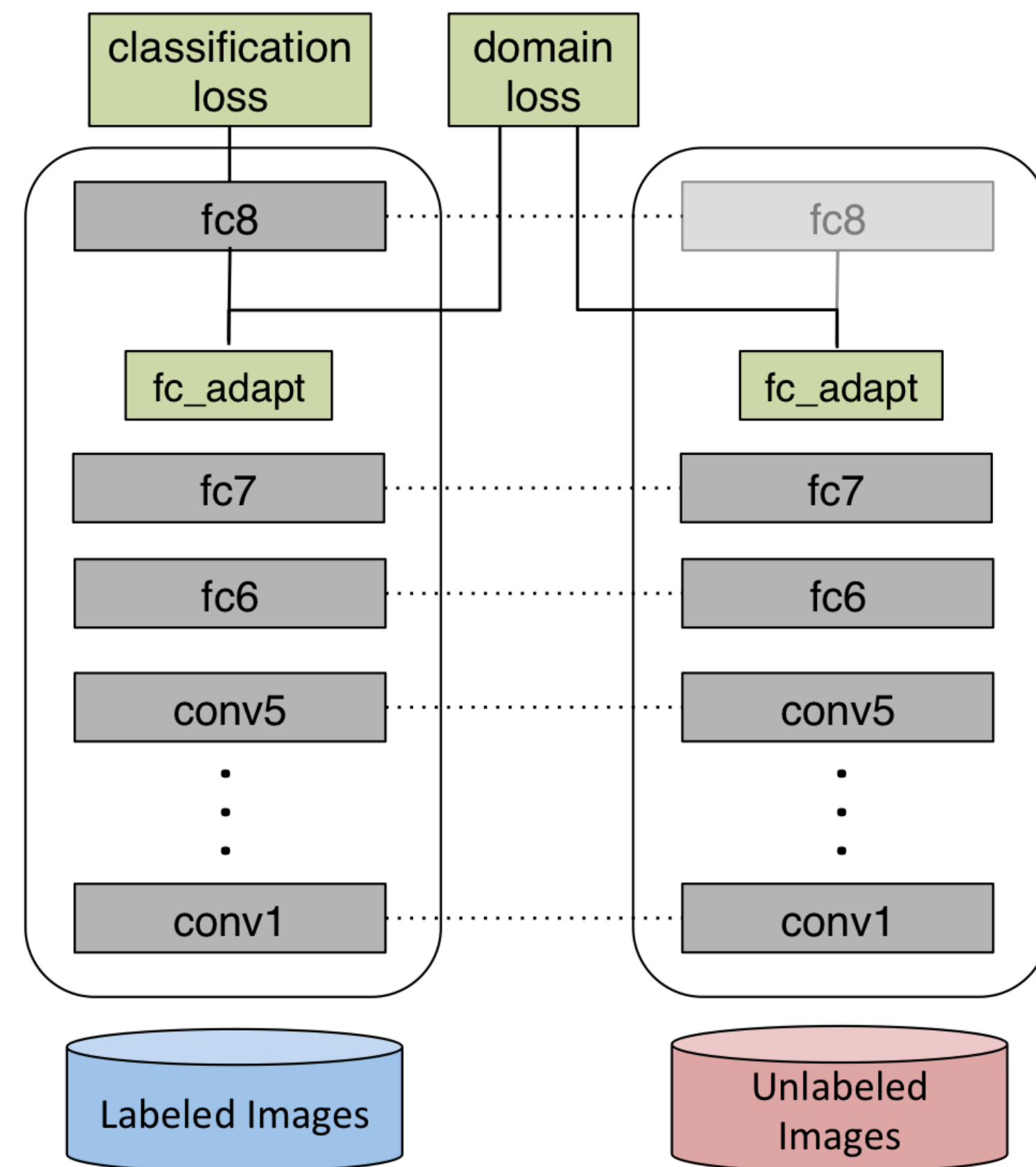
where

$$\mathbf{q}_s = \mathbf{W}_1^\top \mathbf{x}_s + \mathbf{b}, \quad \bar{\mathbf{q}}_t = \mathbf{W}_1^\top \mathbf{x}_t + \mathbf{b}$$



# Core Methods

## Deep Domain Confusion: Maximizing for Domain Invariance [3]



Improvement: Deeper network (Alexnet).

[3] Tzeng E, Hoffman J, Zhang N, et al. Deep domain confusion: Maximizing for domain invariance. arXiv preprint arXiv:1412.3474, 2014

# Core Methods

## Learning Transferable Features with Deep Adaption Networks [4]

Multiple Kernel variant of Maximum Mean Discrepancy (MMD):

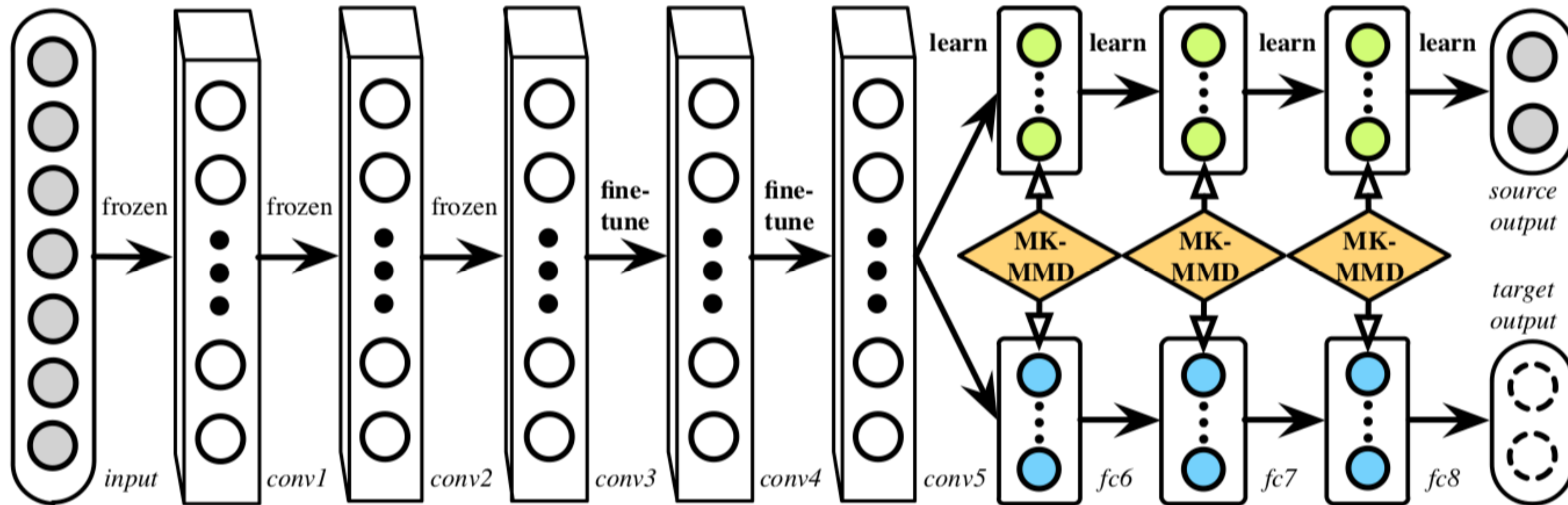
$$\begin{aligned} \mathcal{MMD}_e(\mathbf{x}_s, \mathbf{x}_t) &= \left\| \frac{1}{n_s} \sum_{i=1}^{n_s} \phi(\mathbf{x}_s^{(i)}) - \frac{1}{n_t} \sum_{j=1}^{n_t} \phi(\mathbf{x}_t^{(j)}) \right\|_{\mathcal{H}} \\ &= \left( \frac{1}{n_s^2} \sum_{i=1}^{n_s} \sum_{j=1}^{n_s} k(\mathbf{x}_s^{(i)}, \mathbf{x}_s^{(j)}) + \frac{1}{n_t^2} \sum_{i=1}^{n_t} \sum_{j=1}^{n_t} k(\mathbf{x}_t^{(i)}, \mathbf{x}_t^{(j)}) \right. \\ &\quad \left. - \frac{2}{n_s n_t} \sum_{i=1}^{n_s} \sum_{j=1}^{n_t} k(\mathbf{x}_s^{(i)}, \mathbf{x}_t^{(j)}) \right)^{\frac{1}{2}} \\ &= \left( \frac{\text{Tr}(\mathbf{K}_{xss})}{n_s^2} + \frac{\text{Tr}(\mathbf{K}_{xtt})}{n_t^2} - 2 \frac{\text{Tr}(\mathbf{K}_{xst})}{n_s n_t} \right)^{\frac{1}{2}}, \end{aligned} \quad \rightarrow \quad \mathcal{K} := \left\{ k : k = \sum_{u=1}^d \beta_u k_u, \sum_{u=1}^d \beta_u = D, \beta_u \geq 0, \forall u \in \{1, \dots, d\} \right\}$$

[4] Long M, Cao Y, Wang J, et al. Learning transferable features with deep adaptation networks. In ICML, 2015.

# Core Methods

## Learning Transferable Features with Deep Adaption Networks

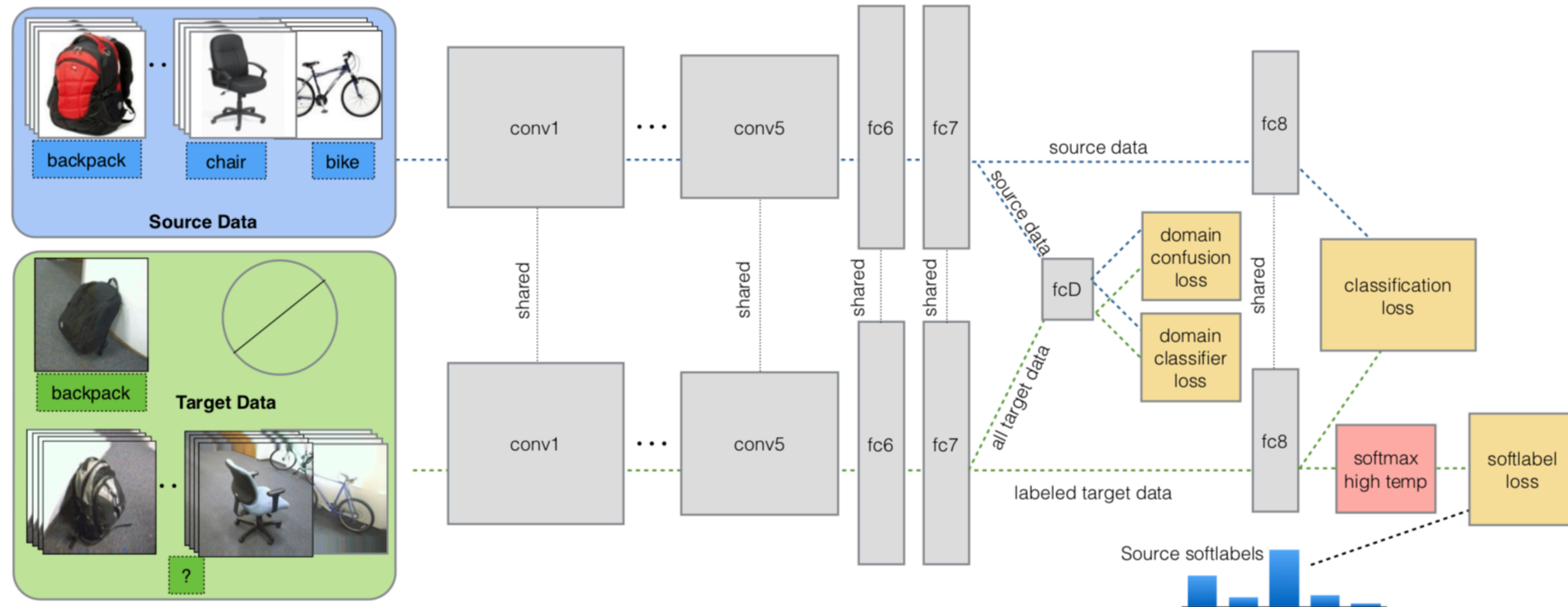
Adaption on multiple layers:



$$\min_{\Theta} \frac{1}{n_a} \sum_{i=1}^{n_a} J(\theta(\mathbf{x}_i^a), y_i^a) + \lambda \sum_{l=l_1}^{l_2} d_k^2(\mathcal{D}_s^l, \mathcal{D}_t^l)$$

# Core Methods

Simultaneous deep transfer across domains and tasks [5]



[5] Tzeng, E., Hoffman, J., Darrell, T., and Saenko, K. (2015). Simultaneous deep transfer across domains and tasks. In ICCV, 2015.



# Core Methods

## Simultaneous deep transfer across domains and tasks

$$\mathcal{L}_C(x, y; \theta_{\text{repr}}, \theta_C) = - \sum_k \mathbb{1}[y = k] \log p_k$$

1

$$\min_{\theta_D} \mathcal{L}_D(x_S, x_T, \theta_{\text{repr}}; \theta_D)$$

$$\min_{\theta_{\text{repr}}} \mathcal{L}_{\text{conf}}(x_S, x_T, \theta_D; \theta_{\text{repr}}).$$

$$\mathcal{L}_D(x_S, x_T, \theta_{\text{repr}}; \theta_D) = - \sum_d \mathbb{1}[y_D = d] \log q_d$$

$$\mathcal{L}_{\text{conf}}(x_S, x_T, \theta_D; \theta_{\text{repr}}) = - \sum_d \frac{1}{D} \log q_d.$$

2

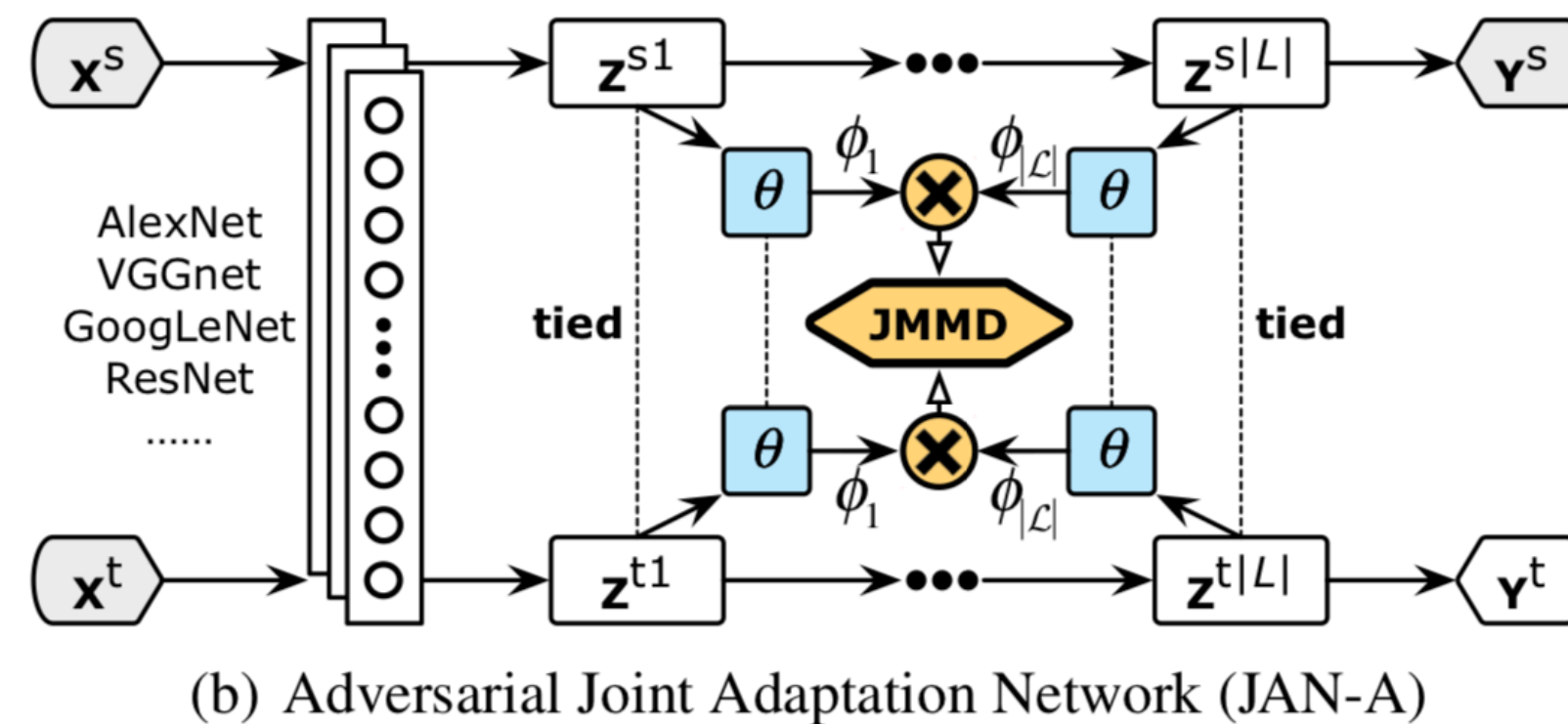
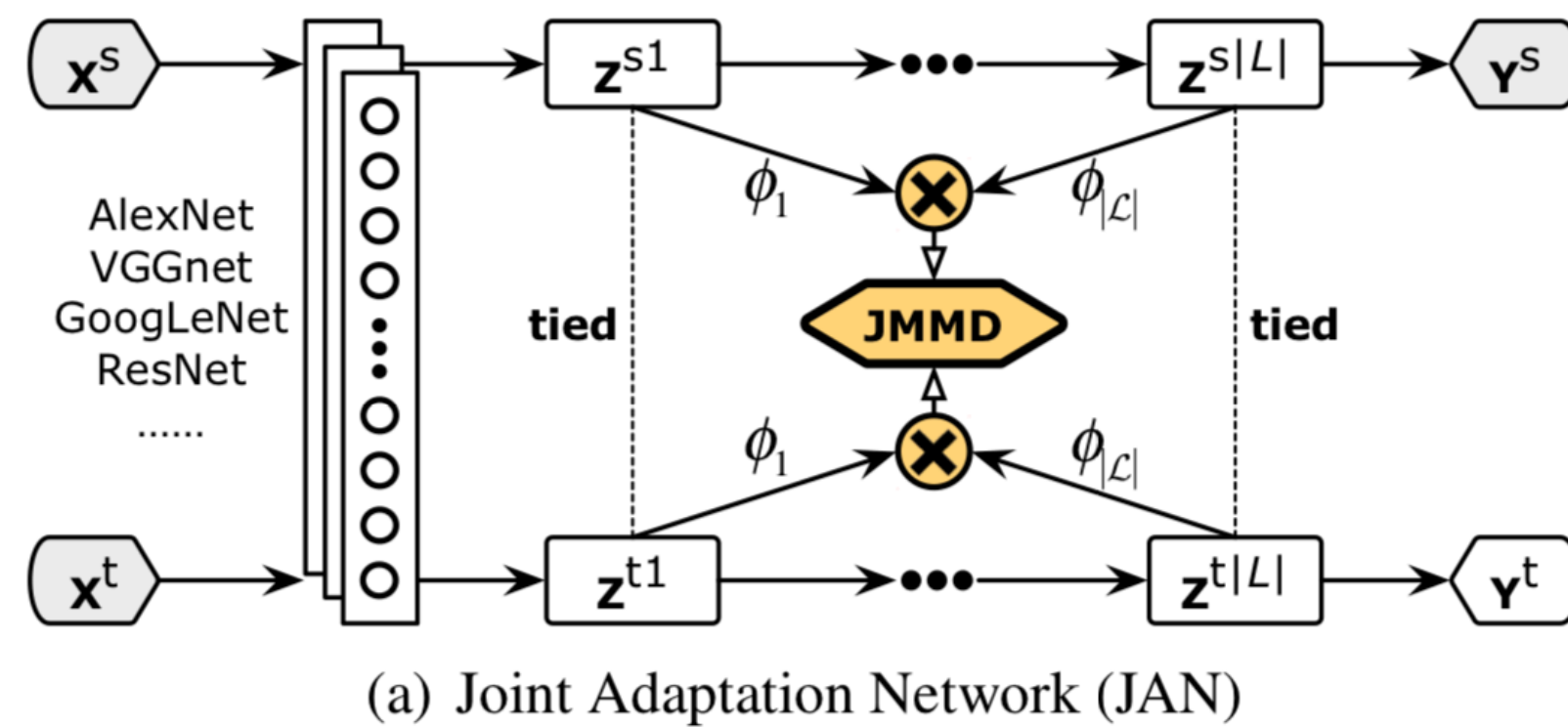
$$\begin{aligned} \mathcal{L}(x_S, y_S, x_T, y_T, \theta_D; \theta_{\text{repr}}, \theta_C) = & \\ & \mathcal{L}_C(x_S, y_S, x_T, y_T; \theta_{\text{repr}}, \theta_C) \\ & + \lambda \mathcal{L}_{\text{conf}}(x_S, x_T, \theta_D; \theta_{\text{repr}}) \\ & + \nu \mathcal{L}_{\text{soft}}(x_T, y_T; \theta_{\text{repr}}, \theta_C). \end{aligned}$$

$$\mathcal{L}_{\text{soft}}(x_T, y_T; \theta_{\text{repr}}, \theta_C) = - \sum_i l_i^{(y_T)} \log p_i$$



# Core Methods

## Deep Transfer Learning with Joint Adaptation Networks [6]



$$\hat{C}_{\mathbf{X}^{1:m}} = \frac{1}{n} \sum_{i=1}^n \otimes_{\ell=1}^m \phi^\ell(\mathbf{x}_i^\ell).$$

$$D_{\mathcal{L}}(P, Q) \triangleq \|\mathcal{C}_{\mathbf{Z}^{s,1:|L|}}(P) - \mathcal{C}_{\mathbf{Z}^{t,1:|L|}}(Q)\|_{\otimes_{\ell=1}^{|L|} \mathcal{H}^\ell}^2$$

$$= \frac{1}{n_s^2} \sum_{i=1}^{n_s} \sum_{j=1}^{n_s} \prod_{\ell \in \mathcal{L}} k^\ell(\mathbf{z}_i^{s\ell}, \mathbf{z}_j^{s\ell})$$

$$+ \frac{1}{n_t^2} \sum_{i=1}^{n_t} \sum_{j=1}^{n_t} \prod_{\ell \in \mathcal{L}} k^\ell(\mathbf{z}_i^{t\ell}, \mathbf{z}_j^{t\ell})$$

$$- \frac{2}{n_s n_t} \sum_{i=1}^{n_s} \sum_{j=1}^{n_t} \prod_{\ell \in \mathcal{L}} k^\ell(\mathbf{z}_i^{s\ell}, \mathbf{z}_j^{t\ell}).$$

$$\min_f \max_{\theta} \frac{1}{n_s} \sum_{i=1}^{n_s} J(f(\mathbf{x}_i^s), \mathbf{y}_i^s) + \lambda \hat{D}_{\mathcal{L}}(P, Q; \theta).$$

[6] Long, M., Wang, J., and Jordan, M. I. Deep transfer learning with joint adaptation networks. In ICML, 2017.

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# Other Methods

## Adaptive Batch Normalization for practical domain adaptation [7]

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**Algorithm 1** Adaptive Batch Normalization (AdaBN)

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**for** neuron  $j$  in DNN **do**

Concatenate neuron responses on all images of target domain  $t$ :  $\mathbf{x}_j = [\dots, x_j(m), \dots]$

Compute the mean and variance of the target domain:  $\mu_j^t = \mathbb{E}(\mathbf{x}_j^t)$ ,  $\sigma_j^t = \sqrt{\text{Var}(\mathbf{x}_j^t)}$ .

**end for**

**for** neuron  $j$  in DNN, testing image  $m$  in target domain **do**

Compute BN output  $y_j(m) := \gamma_j \frac{(x_j(m) - \mu_j^t)}{\sigma_j^t} + \beta_j$

**end for**

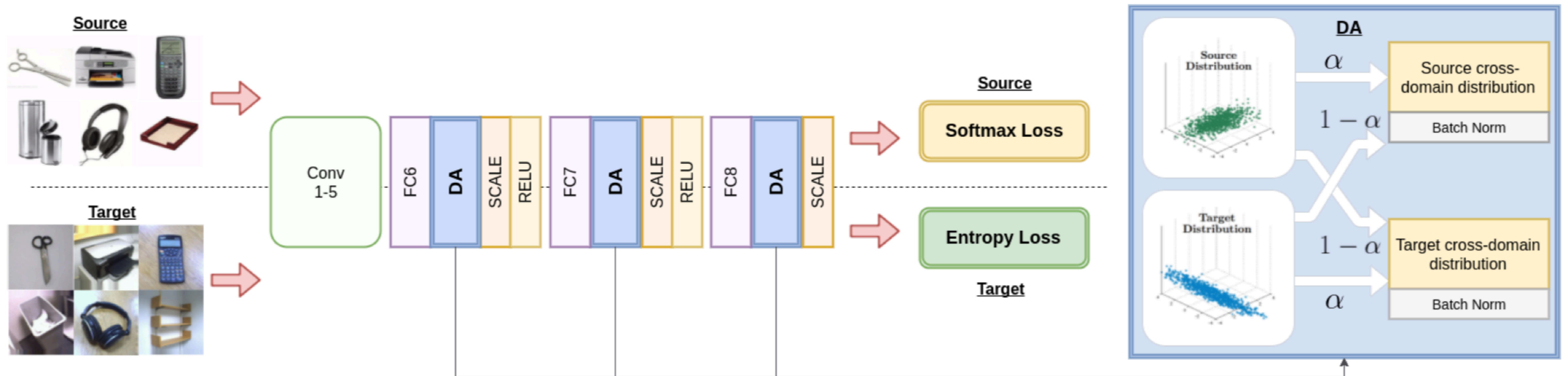
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Utilize the same variance and bias on both domains.

[7] Li, Y., Wang, N., Shi, J., Hou, X., and Liu, J. Adaptive batch normalization for practical domain adaptation. Pattern Recognition, 2018, 80:109–117

# Other Methods

## AutoDIAL: Automatic Domain Alignment Layers [8]



[8] Carlucci, F. M., Porzi, L., Caputo, B., Ricci, E., and Bulò, S. R. AutoDIAL: Automatic domain Alignment Layers. In ICCV, 2017

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# Outlook on Future

- Combination with human knowledge
- Transitive transfer learning
- Online transfer learning
- Transfer reinforcement learning
- ...

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